

# **Machine Building Components**

# SCREWDRIVER FUNCTION MODULES for the automated screw assembly



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# ADVANTAGES

#### Wide product variety for all applications

- Large torque range
- Single- and multi-spindle execution
- Different standard designs

## 1 Standard execution

A slender design for horizontal or vertical screwdriving.

### 2 Short execution

For limited space access.

**3 Underfloor execution** For a vertical, inverted assembly.

#### 4 Vacuum execution

For difficult to access or recessed screwlocations in any assembly-direction.

5 Pick & Place executionFor fasteners presented to a defined pickposition.6 Nut execution

For the automatic feeding and assembly of nuts.



### Maximum east of integration

- Compact, robust design with simple connection ports
- Easy integration into your assembly system

#### Service optimised

- Quick change chuck for a fast bit-exchange within seconds
- Standard bits and sockets reduce
- follow-up costs and downtimes
- It only takes a minute to exchange a screwdriver spindle to perform a calibration or maintenance: Simply loosen one nut!

#### Suitable for a complete process documentation of all screwdriving parameter

- Screwdriver function modules can be equipped with any DEPRAG screwdriver
- Complete acquisition of the processing-data is possible
- Display of torque and angle values
- Display of status on screw-depth and screw-reloading for the next cycle

#### Standard modules allow for short delivery times

- Due to the modular design and the use of many standard components, the screwdriver function module can easily and individually be adapted to fit your application.
- High level of availability and short delivery times

# Axial spring load without the need for special "Inline" bit shaft adapters

Screwdriver spindles always require a stroke compensation. All of our screwdriver spindles are therefore equipped with a lateral guide bolt and spring to regulate the "end load pressure" of each drive spindle. We do not use custom made and/or spring loaded bits or sockets. Internationally available and "standard" bits and sockets are compatible.

### **Stroke variants**



#### Without feeding

for applications with pre-positioned screws

#### With feeding

- for automatic screw presenting through a defined pick position
- spindle-stroke and pick-stroke for lifting the fastener from a pick position

#### With feeding

- for robotic applications with automatic screw feeding through a feedhose
- mouthpiece, guide sleeve and only one actuating cylinder for the spindlestroke



#### Stationary use with feeding

- with automatic screw feeding through a feedhose
- integration into your system
- actuating cylinder for the mouthpiecestroke
- actuating cylinder for the spindle-stroke

#### Underfloor (inverted) use with feeding

- with automatic screw feeding through a feedhose
- for vertical, inverted assemblies; the screwdriver function module is equipped with an additional actuating cylinder
- an additional locking-stroke is applied to the forward-positioned bit to avoid the dropping-back of the screw

# Technical data

Screwdriver function module SFM-L - Light-weight and compact single-spindle design for low torque ranges				
		without feeding	with feeding	
Max. screw head-Ø	mm/in.	no limit	10/0.39	
Max. number of screwdriver spindles		1	1	
Torque	Nm/n.lbs	0.008 - 0.8 / 0.07 - 7.08	0.008 - 0.8 / 0.07 - 7.08	
Mouthpiece stroke	mm/in.	-	25, 80 / 0.98, 3.1	
Spindle stroke	mm/in.	50, 100 / 1.95, 3.9	depends on mouthpiece stroke	
Stroke vacuum finder (only with vacuum execution)	mm/in.	-	50, 100 / 1.95, 3.9	
Stroke socket (only with nut execution)	mm/in.	-	50, 100 / 1.95, 3.9	
Split-jaw nosepiece / ball-type nosepiece length	mm/in.	-	40, 80 / 1.56, 3.1	
Operating modes		pneumatic	pneumatic	
		electric	electric	
Possible stroke variants		A/B	C/D/E	
Distance from mounting surface to screw axis (a)	mm/in.	61 / 2.38	61 / 2.38	
Weight	kg/lbs.	2 / 4.4	5 / 11	

Additional strokes and other types of nosepieces are available on request.

Screwdriver function module SFM-N - Compact single-spindle design for a wide torque range				
		without feeding	with feeding	
Max. screw head-Ø	mm/in.	no limit	14 / 0.55	
Max. number of screwdriver spindles		1	1	
Torque	Nm/n.lbs	0.06 - 20 / 0.53 - 177	0.06 - 20 / 0.53 - 177	
Mouthpiece stroke	mm/in.	-	25, 80 / 0.98, 3.1	
Spindle stroke	mm/in.	50, 100 / 1.95, 3.9	depends on mouthpiece stroke	
Stroke vacuum finder (only with vacuum execution)	mm/in.	-	50, 100 / 1.95, 3.9	
Stroke socket (only with nut execution)	mm/in.	-	50, 100 / 1.95, 3.9	
Split-jaw nosepiece / ball-type nosepiece length	mm/in.	-	40, 80 / 1.56, 3.1	
Operating modes		pneumatic	pneumatic	
		electric	electric	
Possible stroke variants		A / B	C/D/E	
Distance from mounting surface to screw axis (a)	mm/in.	94 / 3.67	94 / 3.67	
Weight	kg/lbs.	5/11	8 / 17.6	
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Additional strokes and other types of nosepieces are available on request.

### **Technical data**

Screwdriver function module SFM-S - Robust multi-spindle design for the use of multiple screwdrivers and high down-load forces				
		without feeding	with feeding	
Max. screw head-Ø	mm/in.	no limit	14 / 0.55	
Max. number of screwdriver spindles		10 *)	10 *)	
Torque	Nm/n.lbs	adapted to application	adapted to application	
Mouthpiece stroke	mm/in.	-	25, 80 / 0.98, 3.1	
Spindle stroke	mm/in.	50, 100 / 1.95, 3.9	depends on mouthpiece stroke	
Stroke vacuum finder (only with vacuum execution)	mm/in.	-	50, 100 / 1.95, 3.9	
Stroke socket (only with nut execution)	mm/in.	-	50, 100 / 1.95, 3.9	
Split-jaw nosepiece / ball-type nosepiece length	mm/in.	-	40, 80 / 1.56, 3.1	
Operating modes		pneumatic	pneumatic	
		electric	electric	
Possible stroke variants		as customer's requirement	as customer's requirement	
Distance from mounting surface to screw axis (a)		adapted to application	adapted to application	
Weight		depends on application	depends on application	

Additional strokes and other types of nosepieces are available on request.

\*) It is possible to use more than 10 screwdriver spindles. Please contact us.

### **Optional Control- and Add-On Functions**

# Screwdriver Shut-Off Control - for pneumatic spindle by PE-Switch Depth Control

	Туре	Control Function
digital	single	<ul> <li>Screw-head is seated and assembly is OK</li> <li>Screw-head is not seated – screw is not completely assembled</li> </ul>
	double	<ul> <li>Screw-head is seated and assembly is OK</li> <li>Screw-head is not seated         – screw is not completely assembled</li> <li>Screw is over-tightened – part is damaged</li> </ul>
analog	absolute	<ul> <li>Screw-head is seated and assembly is OK</li> <li>Screw-head is not seated – screw is not completely assembled</li> <li>Screw is over-tightened – part is damaged</li> <li>Depth control for different levels of screw-locations</li> </ul>
	relative	<ul> <li>Screw-head is seated and assembly is OK</li> <li>Screw-head is not seated – screw is not completely assembled</li> <li>Screw is over-tightened – part is damaged</li> <li>Depth control relative to the screw-head surface of the part</li> </ul>

To support your design efforts, we can supply you with CAD data.



Please contact us.

### MAS-SYSTEM - Increase Process Reliability, Reduce Down-time, Save costs!





Advantage

- Pre-feeding of the screw during a screw assembly cycle is possible
   = cycle time optimisation
- Actively controlled pre-feeding tube tooling minimizes friction contact
   = reduced wear

Difficult accessibility to the screw position? Space is too restricted for any kind of nosepiece or jaw type tooling?

The MAS-System from DEPRAG in combination with a Vacuum-SFM offers the highest process reliability for restricted access screw positions. The screw is blown through a feed tube to the MAS-system where the screw is loaded onto a pick finder which is, in many cases, no larger in diameter than the head of the screw. The screw is held securely in the vertical plane (no tilting) and the "active" two piece jaws allow the screw finder to pass through with zero friction.



Screwdriver function module with MAS



#### **Function**

The screw is blow fed through a feed-tube to the MAS-System where the screw is actively controlled onto the vacuum finder. The vacuum SFM positions the vacuum finder and the correct positioning of the screw on the finder is determined by inspection of the pressure differential. After the successful screw-to-finder transfer the active jaws are opened. Friction between the vacuum finder and the jaw tooling is completely avoided. Additionally the active jaws allow contact free passage of the screw on the vacuum finder and the screw is controlled on plane with the vacuum finder (even for horizontal or inverted applications).

After a successful screw assembly cycle the complete system returns to the home position, the active jaws are closed and the process starts again.

## Inquiry form Screwdriver Function Module

Please submit your application requirements; our application consultants are standing by:

Automatic Screwfeeding	yes	no	
Operating Mode of Screwdriver	pneumatic	electric	
Fastener	Screw Type: Size:	Nut Type: Size:	Threaded Insert Type: Size:
Screwdriver Data			
<u></u>	Speed		rpm
	Torque		Nm
ece Strok	Screw Depth		mm
Mouthpi	Feed Stroke		mm
	Height of interference		mm
Type of Assembly	To Depth		To Torque
	To Angle electronic Screwdriver		
Screwdriving Direction	vertical from above	vertical from below	horizontal
Number of screw-locations:			
Desired Cycle time:		S	
Description of your Application			



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